

MS5803-14BA

Miniature 14 bar Module

SPECIFICATIONS

- High resolution module, 0.2 mbar
- Fast conversion down to 1 ms
- Low power, 1 μA (standby < 0.15 μA)
- Integrated digital pressure sensor (24 bit $\Delta\Sigma$ ADC)
- Supply voltage 1.8 to 3.6 V
- Operating range: 0 to 14 bar, -40 to +85 °C
- I²C and SPI interface (Mode 0,3)
- No external components (Internal oscillator)
- Excellent long term stability
- Hermetically sealable for outdoor devices

The MS5803-14BA is a new generation of high resolution pressure sensors with SPI and I2C bus interface. It is optimized for depth measurement systems with a water depth resolution of 1cm and below. The sensor module includes a high linear pressure sensor and an ultra low power 24 bit $\Delta\Sigma$ ADC with internal factory calibrated coefficients. It provides a precise digital 24 Bit pressure and temperature value and different operation modes that allow the user to optimize for conversion speed and current consumption. A high resolution temperature output allows the implementation of a depth measurement systems and thermometer function without any additional sensor. The MS5803-14BA can be interfaced to any microcontroller. The communication protocol is simple, without the need to programming internal registers in the device. The gel protection and antimagnetic stainless steel cap protects against 30 bar overpressure water resistant. This new sensor module generation is based on leading MEMS technology and latest benefits from the Intersema's proven experience and know-how in high volume manufacturing of pressure modules have been widely used for over a decade. This sensing principle employed leads to very low hysteresis and high stability of both pressure and temperature signal.

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FEATURES

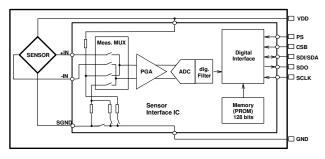
FIELD OF APPLICATION

- Mobile water depth measurements systems
- Diving computers
- Adventure or multi-mode watches

TECHNICAL DATA

| Sensor Performances (VDD = 3 V) | | | | | | | | | |
|--|-------|--------------------|---------|---------|--|--|--|--|--|
| Pressure | Min | Тур | Max | Unit | | | | | |
| Range | 0 | | 14 | bar | | | | | |
| ADC | | 24 | | bit | | | | | |
| Resolution (1) | 1/ | 0.6 / 0.4 / 0.2 | / 0.3 | mbar | | | | | |
| Accuracy 0°C to +40°C, 0 to 6 bar (2) | -20 | | +20 | mbar | | | | | |
| Accuracy -40°C to + 85°C 0 to 6 bar (2) | -40 | | +40 | mbar | | | | | |
| Response time | 0.5 / | 1.1 / 2.1 8.22 | / 4.1 / | ms | | | | | |
| Long term stability | | -20 | | mbar/yr | | | | | |
| Temperature | Min | Тур | Max | Unit | | | | | |
| Range | -40 | | +85 | °C | | | | | |
| Resolution | | <0.01 | | °C | | | | | |
| Accuracy | -0.8 | | +0.8 | °C | | | | | |
| Notes: (1) Oversampling Ratio: 256 / 512 / 1024 / 2048 / 4096 (2) With autozero at one pressure point | | | | | | | | | |

FUNCTIONAL BLOCK DIAGRAM



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PERFORMANCE SPECIFICATIONS

ABSOLUTE MAXIMUM RATINGS

| Parameter | Symbol | Conditions | Min. | Тур. | Max | Unit |
|----------------------------------|------------------|-------------------------|------|------|------|------|
| Supply voltage | V _{DD} | | -0.3 | | +4.0 | V |
| Storage temperature | Ts | | -40 | | +125 | °C |
| Overpressure | P _{max} | ISO 6425 | | | 30 | bar |
| Maximum Soldering Temperature | T _{max} | 40 sec max | | | 250 | °C |
| ESD rating | | Human Body Model | -4 | | +4 | kV |
| Latch up | | JEDEC standard No 78 | -100 | | +100 | mA |

ELECTRICAL CHARACTERISTICS

| Parameter | Symbol | Conditions | Min. | Тур. | Max | Unit |
|---------------------------------------|--------|---|------|----------------------------------|------|------|
| Operating Supply voltage | VDD | | 1.8 | 3.0 | 3.6 | V |
| Operating Temperature | Т | | -40 | +25 | +85 | °C |
| Supply current (1 sample per sec.) | IDD | OSR 4096 2048 1024 512 256 | | 12.5 6.3 3.2 1.7 0.9 | | μΑ |
| Peak supply current | | during conversion | | 1.4 | | mA |
| Standby supply current | | at 25°c | | 0.02 | 0.14 | μA |
| VDD Capacitor | | From VDD to GND | 100 | | | nF |

ANALOG DIGITAL CONVERTER (ADC)

| Parameter | Symbol | Conditions | Min. | Тур. | Max | Unit |
|-----------------|--------|---|--------------------------------------|--------------------------------------|--------------------------------------|------|
| Output Word | | | | 24 | | bit |
| Conversion time | tc | OSR 4096 2048 1024 512 256 | 7.40 3.72 1.88 0.95 0.48 | 8.22 4.13 2.08 1.06 0.54 | 9.04 4.54 2.28 1.17 0.60 | ms |

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PERFORMANCE SPECIFICATIONS (CONTINUED)

PRESSURE OUTPUT CHARACTERISTICS (V_{DD} = 3 V, T = 25°C UNLESS OTHERWISE NOTED)

| Parameter | Condition | าร | Min. | Тур. | Max | Unit |
|---|------------------------------|----------------------|---------------------|-------------------|--------------------|---------|
| Operating Pressure Range | Prange | Full Accuracy | 0 | | 14 | bar |
| Absolute Accuracy, Temperature range 0 40 °C | 0 6 ba 0 10 ba 0 14 ba | ar | -20 -60 -150 | | +20 +20 +20 | mbar |
| Absolute Accuracy, Temperature range -40 85 °C | 0 6 ba 0 10 ba 0 14 ba | ar | -40 -120 -200 | | +40 +80 +100 | mbar |
| Maximum error with supply voltage (1) | V _{DD} = 1.8 | V 3.6 V | | +/-20 | | mbar |
| Long-term stability | | | | -20 | | mbar/yr |
| Resolution BMS | OSR | 4096 2048 1024 | | 0.2 0.3 0.4 | | mbar |
| | | 512 256 | | 0.4 0.6 1.0 | | moul |

(1) With autozero at 3V point

TEMPERATURE OUTPUT CHARACTERISTICS (V_{DD} = 3 V, T = 25°C UNLESS OTHERWISE NOTED)

| Parameter | Conditions | | Min. | Тур. | Max | Unit |
|---------------------------------------|-------------------------------|------|------|--------|------|------|
| | 010 bar | | -0.8 | | +0.8 | |
| Absolute Accuracy | -2085°C | | -2.0 | | +2.0 | °C |
| | -4085°C | | -4.0 | | +4.0 | |
| Maximum error with supply voltage (1) | V _{DD} = 1.8 V 3.6 V | | | +/-0.5 | | °C |
| | OSR | 4096 | | 0.002 | | |
| | | 2048 | | 0.003 | | |
| Resolution RMS | | 1024 | | 0.005 | | °C |
| | | 512 | | 0.008 | | |
| | | 256 | | 0.012 | | |

(1) With autozero at 3V point

PERFORMANCE SPECIFICATIONS (CONTINUED)

DIGITAL INPUTS (PS, CSB, DIN, SCLK, SDA, SCL)

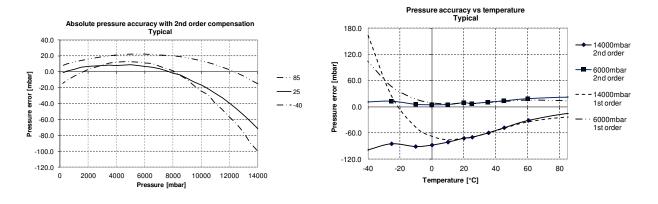
| Parameter | Symbol | Conditions | Min. | Тур. | Max | Unit |
|-------------------------------|-----------|--------------|---------------------|------|---------------------|------|
| Serial data clock | SCLK | SPI protocol | | | 20 | MHz |
| Serial data clock | SCL | I2C protocol | | | 400 | kHz |
| Input high voltage | VIH | Pins CSB | 80% V _{DD} | | 100% Vdd | V |
| Input low voltage | VIL | | 0% V _{DD} | | 20% V _{DD} | V |
| Input leakage current | Ileak25°C | at 25°c | | | 0.15 | μA |
| CS low to first SCLK rising | tCSL | | 21 | | | ns |
| CS low from last SCLK falling | tCSH | | 21 | | | ns |

PRESSURE OUTPUTS (DOUT, SDA, SCL)

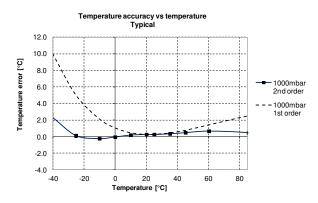
| Parameter | Symbol | Conditions | Min. | Тур. | Max | Unit |
|---------------------|-----------------|------------------------------|---------------------|------|---------------------|------|
| Output high voltage | Vон | I _{source} = 0.6 mA | 80% V _{DD} | | 100% Vdd | V |
| Output low voltage | V _{OL} | I _{sink} = 0.6 mA | 0% V _{DD} | | 20% V _{DD} | V |
| Load capacitance | CLOAD | | | 16 | | рF |

PERFORMANCE CHARACTERISTICS

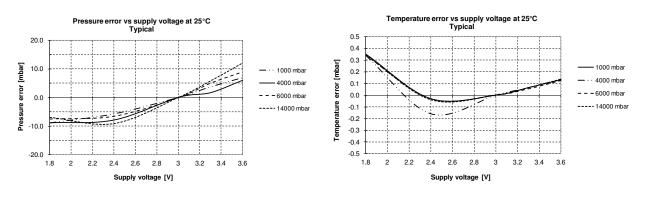
PRESSURE ERROR VS PRESSURE AND TEMPERATURE



TEMPERATURE ERROR VS TEMPERATURE



PRESSURE AND TEMPERATURE ERROR VS POWER SUPPLY



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FUNCTIONAL DESCRIPTION

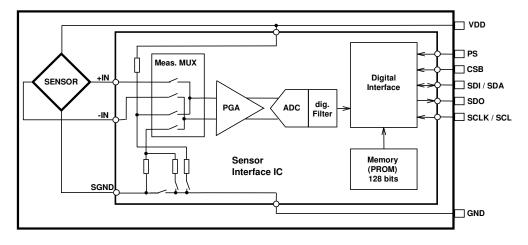


Figure 1: Block diagram of MS5803-14BA

GENERAL

The MS5803-14BA consists of a piezo-resistive sensor and a sensor interface IC. The main function of the MS5803-14BA is to convert the uncompensated analogue output voltage from the piezo-resistive pressure sensor to a 24bit digital value, as well as providing a 24-bit digital value for the temperature of the sensor.

FACTORY CALIBRATION

Every module is individually factory calibrated at two temperatures and two pressures. As a result, 6 coefficients necessary to compensate for process variations and temperature variations are calculated and stored in the 128bit PROM of each module. These bits (partitioned into 6 coefficients W1 to W6) must be read by the microcontroller software and used in the program converting D1 and D2 into compensated pressure and temperature values. The 2 coefficients W0 and W7 are for factory configuration and CRC.

SERIAL INTERFACE

The MS5803-14BA has built in two types of serial interfaces: SPI and I²C. Pulling the Protocol Select pin PS to low selects the SPI protocol, pulling PS to high activates the I²C bus protocol.

| Pin PS | Mode | Pins used |
|--------|------------------|---------------------|
| High | I ² C | SDA, SCL, CSB |
| Low | SPI | SDI, SDO, SCLK, CSB |

SPI MODE

The external microcontroller clocks in the data through the input SCLK (Serial CLocK) and SDI (Serial Data In). In the SPI mode module can accept both mode 0 and mode 3 for the clock polarity and phase. The sensor responds on the output SDO (Serial Data Out). The pin CSB (Chip Select) is used to enable/disable the interface, so that other devices can talk on the same SPI bus. The CSB pin can be pulled high after the command is sent or after the end of the command execution (for example end of conversion). The best noise performance from the module is obtained when the SPI bus is quiet and without communication to other devices during the ADC conversion in progress.

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I²C MODE

The external microcontroller clocks in the data through the input SCLK (Serial CLocK) and SDA (Serial DAta). The sensor responds on the same pin SDA which is bidirectional for the I²C bus interface. So this interface type uses only 2 signal lines and does not require a chip select, which can be favourable to reduce board space. In I²C-Mode the complement of the pin CSB (Chip Select) represents the LSB of the I²C address. It is possible to use two sensors with two different addresses on the I²C bus. The pin CSB shall be connected to VDD or GND (do not leave unconnected!).

| Pin CSB | Address (7 bits) |
|---------|------------------|
| High | 0x76 (1110110 b) |
| Low | 0x77 (1110111 b) |

COMMANDS

The MS5803-14BA has only five basic commands:

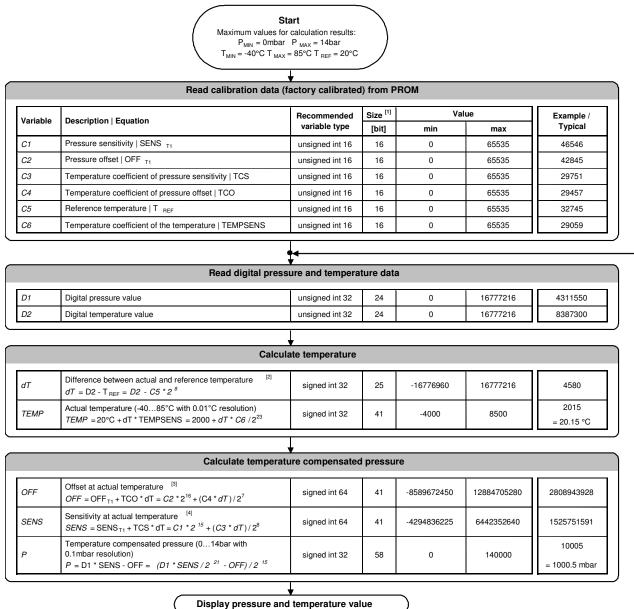
- 1. Reset
- 2. Read PROM (128 bit of calibration words)
- 3. D1 conversion
- 4. D2 conversion
- 5. Read ADC result (24 bit pressure / temperature)

Size of each command is 1 byte (8 bits) as described in the table below. After ADC read commands the device will return 24 bit result and after the PROM read 16bit result. The address of the PROM is embedded inside of the PROM read command using the a2, a1 and a0 bits.

| | Com | mand I | byte | | | | | | hex value |
|-----------------------|---------|--------|------|-----|-------------|-------------|-------------|------|-----------------|
| Bit number | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | |
| Bit name | PR M | COV | - | Тур | Ad2/ Os2 | Ad1/ Os1 | Ad0/ Os0 | Stop | |
| Command | | | | | | | | | |
| Reset | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 0 | 0x1E |
| Convert D1 (OSR=256) | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0x40 |
| Convert D1 (OSR=512) | 0 | 1 | 0 | 0 | 0 | 0 | 1 | 0 | 0x42 |
| Convert D1 (OSR=1024) | 0 | 1 | 0 | 0 | 0 | 1 | 0 | 0 | 0x44 |
| Convert D1 (OSR=2048) | 0 | 1 | 0 | 0 | 0 | 1 | 1 | 0 | 0x46 |
| Convert D1 (OSR=4096) | 0 | 1 | 0 | 0 | 1 | 0 | 0 | 0 | 0x48 |
| Convert D2 (OSR=256) | 0 | 1 | 0 | 1 | 0 | 0 | 0 | 0 | 0x50 |
| Convert D2 (OSR=512) | 0 | 1 | 0 | 1 | 0 | 0 | 1 | 0 | 0x52 |
| Convert D2 (OSR=1024) | 0 | 1 | 0 | 1 | 0 | 1 | 0 | 0 | 0x54 |
| Convert D2 (OSR=2048) | 0 | 1 | 0 | 1 | 0 | 1 | 1 | 0 | 0x56 |
| Convert D2 (OSR=4096) | 0 | 1 | 0 | 1 | 1 | 0 | 0 | 0 | 0x58 |
| ADC Read | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0x00 |
| PROM Read | 1 | 0 | 1 | 0 | Ad2 | Ad1 | Ad0 | 0 | 0xA0 to 0xAE |

Figure 2: Command structure

PRESSURE AND TEMPERATURE CALCULATION



Maximal size of intermediate result during evaluation of variable [1]

[2] min and max have to be defined

Notes

- [3] [4] min and max have to be defined
 - min and max have to be defined

Figure 3: Flow chart for pressure and temperature reading and software compensation.

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SECOND ORDER TEMPERATURE COMPENSATION

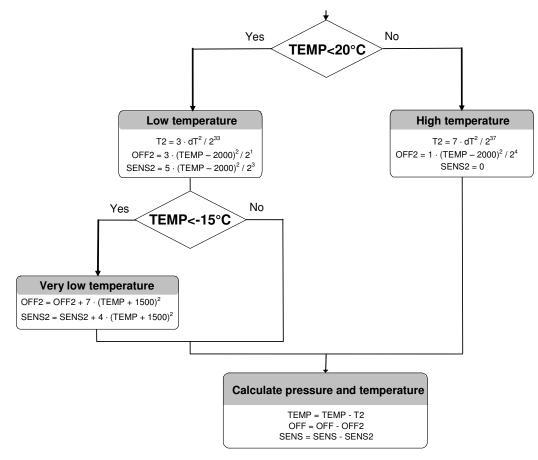


Figure 4: Flow chart for pressure and temperature to the optimum accuracy.

SPI INTERFACE

RESET SEQUENCE

The Reset sequence shall be sent once after power-on to make sure that the calibration PROM gets loaded into the internal register. It can be also used to reset the device ROM from an unknown condition

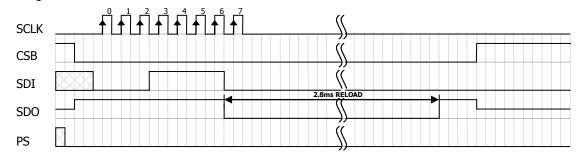


Figure 5: Reset command sequence SPI mode 0

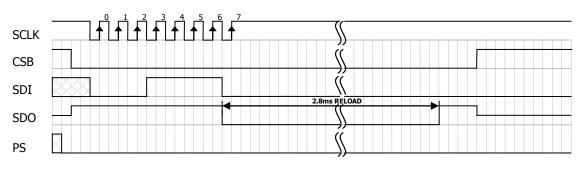


Figure 6: Reset command sequence SPI mode 3

CONVERSION SEQUENCE

The conversion command is used to initiate uncompensated pressure (D1) or uncompensated temperature (D2) conversion. The chip select can be disabled during this time to communicate with other devices.

After the conversion, using ADC read command the result is clocked out with the MSB first. If the conversion is not executed before the ADC read command, or the ADC read command is repeated, it will give 0 as the output result. If the ADC read command is sent during conversion the result will be 0, the conversion will not stop and the final result will be wrong. Conversion sequence sent during the already started conversion process will yield incorrect result as well.

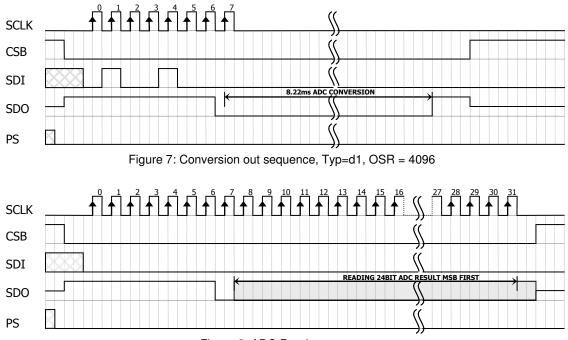
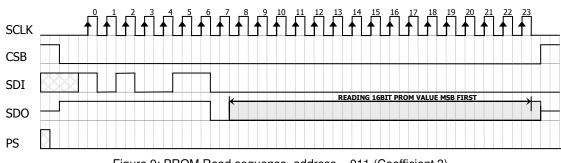
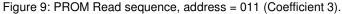


Figure 8: ADC Read sequence

PROM READ SEQUENCE

The read command for PROM shall be executed once after reset by the user to read the content of the calibration PROM and to calculate the calibration coefficients. There are in total 8 addresses resulting in a total memory of 128 bit. Address 0 contains factory data and the setup, addresses 1-6 calibration coefficients and address 7 contains the serial code and CRC. The command sequence is 8 bits long with a 16 bit result which is clocked with the MSB first.





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I²C INTERFACE

COMMANDS

Each I²C communication message starts with the start condition and it is ended with the stop condition. The MS5803-14BA address is 111011Cx, where C is the complementary value of the pin CSB. Since the IC does not have a microcontroller inside, the commands for I²C and SPI are quite similar.

RESET SEQUENCE

The reset can be sent at any time except when the power on did not work it could be possible that the acknowledge blocks the SDA. When SDA is blocked by an undefined state the only way to get the MS5803-14BA to work is to send a power on reset.

| | 1 1 1 0 1 1 Device Addres | | 0 0 0 1 1 1 command | 1 0 0 | |
|---|------------------------------|-----------------------|------------------------|-----------------------|--|
| S | Device Addres | s W A | cmd byte | AP | |
| | From Master From Slave | S = Start P = Stop | | W = Write R = Read | A = Acknowledge N = Not Acknowledge |



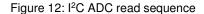
CONVERSION SEQUENCE

A conversion can be started by sending the command to MS5803-14BA. When command is sent to the system it stays busy until conversion is done. When conversion is finished the data can be accessed by sending a Read command, when an acknowledge appears from the MS5803-14BA, you may then send 24 SCLK cycles to get all result bits. Every 8 bit the system waits for an acknowledge signal.

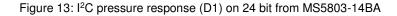
| 1 1 1 0 1 Device Addres | | 0 1 0 0 1 0 command | 0 0 0 | |
|----------------------------|---------------------------|------------------------|-----------------------|--|
| S Device Addres | s W A | cmd byte | A P | |
| From Master From Slave | S = Start (P = Stop (| | W = Write R = Read | A = Acknowledge N = Not Acknowledge |

Figure 11: I²C Command to initiate a pressure conversion (OSR=4096, typ=D1)

| 1 1 1 0 1 1 CSB Device Address | 0 0 | 0 0 0 0 0 0 command | 0 0 0 | |
|-----------------------------------|-----|------------------------|-----------------------|--|
| S Device Address | WA | cmd byte | AP | |
| | | Condition Condition | W = Write R = Read | A = Acknowledge N = Not Acknowledge |



| 1 1 1 0 1 1 Device Address | CSB 1 0 X | X X X X X X X data | 0 X X | X X X X X X data | 0 | X X X X X X X X X 0 data |
|-------------------------------|---------------------------------|-----------------------|-------|--------------------------------------|----|-----------------------------|
| S Device Address | R A | Data 23-16 | Α | Data 8 - 15 | Α | Data 7 - 0 N P |
| | S = Start Cono P = Stop Cono | | | A = Acknowledge N = Not Acknowled | ge | |



PROM READ SEQUENCE

The PROM Read command consists of two parts. First command sets up the system into PROM read mode. The second part gets the data from the system.

| 1 1 0 1 CSB 0 1 0 1 0 0 Device Address Command Command A P | | | | | | | | |
|--|---|-----------|-------------------------|--|--|--|--|--|
| From MasterS = Start ConditionW = WriteA = AcknowledgeFrom SlaveP = Stop ConditionR = ReadN = Not Acknowledge | | | | | | | | |
| Figure 11: I ² C Con | Figure 11: I ² C Command to read memory address= 011 (Coefficient 3) | | | | | | | |
| 1 1 1 0 1 1 CSB Device Address | 10XXXXX data | x x x o x | X X X X X X X 0 data | | | | | |
| 5 Device Address | R A Memory bit 1 | 5-8 A | Memory bit 7 - 0 N P | | | | | |
| From Master S = Start Condition W = Write A = Acknowledge From Slave P = Stop Condition R = Read N = Not Acknowledage | | | | | | | | |

Figure 14: I²C answer from MS5803-14BA

CYCLIC REDUNDANCY CHECK (CRC)

MS5803-14BA contains a PROM memory with 128-Bit. A 4-bit CRC has been implemented to check the data validity in memory. The application note AN520 describes in detail CRC-4 code used.

| A d d | D B 1 5 | D B 1 4 | D B 1 3 | D B 1 2 | D B 1 1 | D B 1 0 | D B 9 | D B 8 | D B 7 | D B 6 | D B 5 | D B 4 | D B 3 | D B 2 | D B 1 | D B 0 |
|-------------|----------------------------------|------------------|------------------|------------------|------------------|------------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|
| 0 | 16 bit reserved for manufacturer | | | | | | | | | | | | | | | |
| 1 | Coefficient 1 (16 bit unsigned) | | | | | | | | | | | | | | | |
| 2 | Coefficient 2 (16 bit unsigned) | | | | | | | | | | | | | | | |
| 3 | Coefficient 3 (16 bit unsigned) | | | | | | | | | | | | | | | |
| 4 | Coefficient 4 (16 bit unsigned) | | | | | | | | | | | | | | | |
| 5 | Coefficient 5 (16 bit unsigned) | | | | | | | | | | | | | | | |
| 6 | Coefficient 6 (16 bit unsigned) | | | | | | | | | | | | | | | |
| 7 | | | | | | | | | | | | | | CF | RC | |

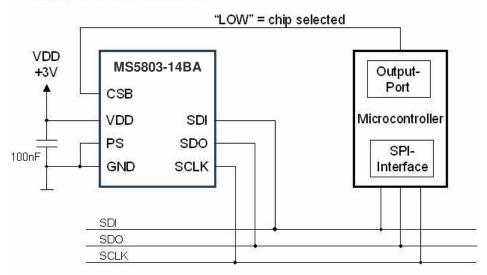
Figure 15: Memory PROM mapping

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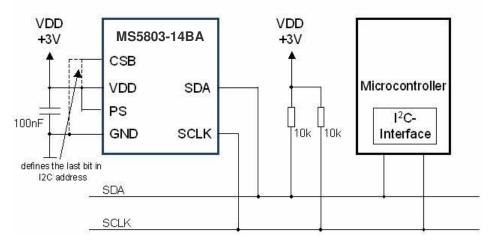
APPLICATION CIRCUIT

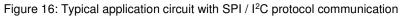
The MS5803-14BA is a circuit that can be used in conjunction with a microcontroller in mobile depth-meter applications. It is designed for low-voltage systems with a supply voltage of 3 V.

SPI protocol communication

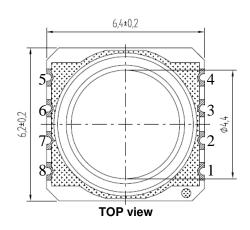


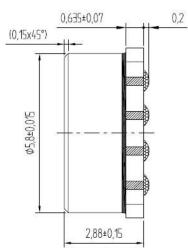
I²C protocol communication

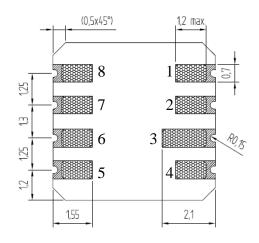




PACKAGE OUTLINE AND PIN CONFIGURATION







| Pin | Name | Туре | Function |
|-----|---------|------|--|
| 1 | SCLK | Ι | Serial data clock |
| 2 | GND | G | Ground |
| 3 | CSB | Ι | Chip Select (active low) |
| 4 | NC | NC | - |
| 5 | VDD | Р | Positive supply voltage |
| 6 | PS | I | Communication protocol select SPI / I2C |
| 7 | SDI/SDA | Ι | Serial data input |
| 8 | SDO | 0 | Serial data output |

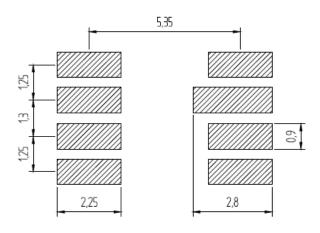
Figure 17: MS5803-14BA package outlines, pin configuration and description

Notes: (1) Dimensions in mm

(2) General tolerance ±0.1

(3) Cap centering ± 0.15 from center of the ceramic

RECOMMENDED PAD LAYOUT

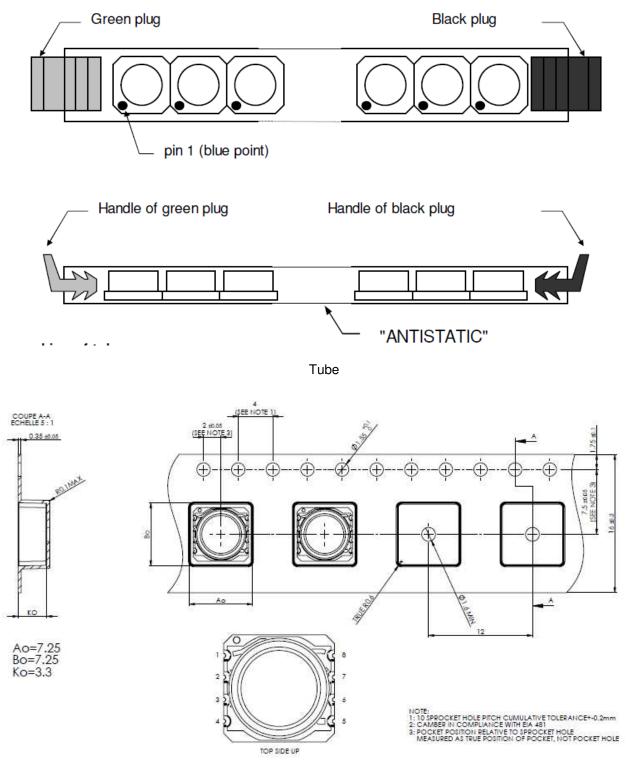


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SHIPPING PACKAGE





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MOUNTING AND ASSEMBLY CONSIDERATIONS

SOLDERING

Please refer to the application note AN808 available on our website for all soldering issues.

MOUNTING

The MS5803-14BA can be placed with automatic Pick & Place equipment using vacuum nozzles. It will not be damaged by the vacuum. Due to the low stress assembly the sensor does not show pressure hysteresis effects. It is important to solder all contact pads.

CONNECTION TO PCB

The package outline of the module allows the use of a flexible PCB for interconnection. This can be important for applications in watches and other special devices.

SEALING WITH O-RINGS

In products like outdoor watches the electronics must be protected against direct water or humidity. For those products the MS5803-14BA provides the possibility to seal with an O-ring. The protective cap of the MS5803-14BA is made of special anticorrosive stainless steel with a polished surface. In addition to this the MS5803-14BA is filled with silicone gel covering the sensor and the bonding wires. The O-ring (or O-rings) shall be placed at the outer diameter of the metal cap. This method avoids mechanical stress because the sensor can move in vertical direction.

CLEANING

The MS5803-14BA has been manufactured under cleanroom conditions. It is therefore recommended to assemble the sensor under class 10'000 or better conditions. Should this not be possible, it is recommended to protect the sensor opening during assembly from entering particles and dust. To avoid cleaning of the PCB, solder paste of type "no-clean" shall be used. Cleaning might damage the sensor!

ESD PRECAUTIONS

The electrical contact pads are protected against ESD up to 4 kV HBM (human body model). It is therefore essential to ground machines and personnel properly during assembly and handling of the device. The MS5803-14BA is shipped in antistatic transport boxes. Any test adapters or production transport boxes used during the assembly of the sensor shall be of an equivalent antistatic material.

DECOUPLING CAPACITOR

Particular care must be taken when connecting the device to the power supply. A 100 nF ceramic capacitor must be placed as close as possible to the MS5803-14BA VDD pin. This capacitor will stabilize the power supply during data conversion and thus, provide the highest possible accuracy.

ORDERING INFORMATION

| Product Code | Product | Art. No | Delivery Form |
|---------------|-------------------------|-----------------|-------------------|
| MS5803-14BA01 | Miniature 14 bar Module | MS580314BA01-00 | Tube |
| MS5803-14BA01 | Miniature 14 bar Module | MS580314BA01-50 | Tape& reel TOP-UP |