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Model : HG-MP40WP



HG-MP40WP (Water Proof Type)

Features

- Multi-function transceiver model for water proof types of ultrasonic sensors
- Two types of transmit modes: Free Run and External Trigger modes
- Free voltage in power supply (DC 6 V \sim 15 V)
- Four kinds of simultaneous output signals
 - Ultrasonic waveform of a received and amplified signal
 - Squared signal in TTL level corresponding to ultrasonic waveform
 - Squared signal that its pulse-width is proportional to distance
 - Independent signal outputs for proximity detection corresponding to five step detection range setting of 1 m interval in distance
- Employing a high performance ASIC Chip
- Detection of obstacles located at a long distance

Specification

Input DC (V)	• 6 ~ 15 (12 V recommended)
Frequency (kHz)	• 40 (Nominal)
Detectable Range in Distance (m)	 0.4 ~ 5 : Distance output 0 ~ 6.5 : Output of proximity detection (five steps)
Size (mm)	 PCB : 56 x 39 x 15 Sensor : Φ16 x 10
Current Consumption (mA) for DC 12 V Input	 10 : standby mode 13 : when an object is detected within the detection range setting Max. 22 : depending on detected distance
Operating Temperature (°C)	• - 30 ~ + 85

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Application

• Distance Measurement, Obstacle detection for AGV and robot, and industrial machinery etc., Outdoor parking lot management, Safety facility management and risk alerts, customers facilities, power saver, and automation equipment, etc.

Description

- Using only a single sensor(transceiver sensor) unit for both transmittance and receiving ultrasonic waves
- Convenient for distance measuring and object detection.
- Two types of transmit mode for convenience
 - Free Run mode : with a power supply, sensor/module itself transmits trigger and burst signal for basic & stand alone application
 - External Trigger : External system(a controller or processor circuit) controls the trigger signals – for advance application such as multi-sensor system
- Input DC voltage is applicable in the wide range from 6 V to 15 V
- Output signal of 5V TTL level is applicable to processor circuit usage or controllers of industrial system.
- Four simultaneous output signals
 - Ultrasonic waveforms of received and amplified signals
 - Squared signals in TTL level corresponding to detected ultrasonic waveforms
 - Squared signal that the pulse-width is proportional to distance
 - Independent signal outputs for proximity detection corresponding to five step detection range setting with the interval of 1 m in distance
 - \rightarrow The detection range setting is 1 m, 2 m, 3 m, 4 m, and longer than 4 m and the accuracy of distance setting is about ± 10% of distance. There are total five steps.
 - → High level signals of DC 5 V are independently outputted at different terminals corresponding to distance when obstacles are detected, respectively.
 - \rightarrow also, lights are turned on at LEDs of the different quantity depending on distance.
 - \rightarrow Therefore, the detection of signals can be used at only one terminal or the combination of several distance setting.
 - % The setting of a special detection range in distance is available for volume orders
- High performance ASIC Chip is mounted in the module for stable transmission and sensitive reception (Maximum amplification is about 5,000 times)
- Long distance detection is available by optimized design

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Part Name

- ① **Input/Output Terminal** : Power, External Trigger input, and three kinds of output signals
- ② <u>Ultrasonic frequency adjusting</u>: Factory tuned for unit for the best performance (Do not adjust it because it was optimized when released!)
- ③ ASIC Chip : 48 pin Chip with many useful functions. (Hagisonic Product)
- Volume resistance for sensitivity(Gain) control, VR : The gain is ranging from 1,000 to 5,000 times. It is 3,000 times when released.
- (5) Sensor Connection Terminal : Coaxial cable is recommended (when longer than 10 Cm)
- (6) <u>Ultrasonic sensor unit</u>: the water proof type of sensor has conventional directivities (appox. 65~75°) and the diameter is 16 mm
- ⑦ Independent signal output terminals for proximity detection corresponding to five step detection range setting with the interval of 1 m in distance
- (a) **LEDs** : lighted at those of different quantity depending on distance.
- Iransmit Mode selection PAD :
 - Free Run Mode : With soldering; approx. 8 Burst per second is generated. (factory option : Soldered)
 - External Trigger Mode : Without soldering; External TTL level Pulse is needed for transmittance

(1~100 times per second is available / Pulse width : 0.5 ~ 1 ms recommended)

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Timing Chart



dd: 16/5 Bldg #2 Zhongko Man

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Timing Chart



- 4th step preset in detection range: 0~ 4 m
- Not detected in 1st preset range (1 m) for object located at 2. 5 m distance. (LOW signal output and LED OFF)
- Not detected in 2nd preset range (2 m) for object located at 2. 5 m distance. (LOW signal output and LED OFF)
- Internally extracted signal when detected in 3nd preset range (3 m) for object located at 2. 5 m distance. (HIGH signal output and LED ON)
- Internally extracted signal when detected in 4th preset range (4 m) for object located at 2. 5 m distance. (HIGH signal output and LED ON)
- Internally extracted signal when detected in arbitrary range including longer distance than 4 m (HIGH signal output and LED ON)

LED lighting status depending on distance of object (⑧ at a figure in 3 page)



- No detection
- Detected in longer distance than 4 m
- Detected in the range from 3 m to 4 m
- Detected in the range from 2 m to 3 m
- Detected in the range from 1 m to 2 m
- Detected in shorter distance than 4 m

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Input / Output Terminal Configuration



Parts Details

- The amplified signal output of received ultrasonic waves (#5 signal in Timing Chart)
- The squared signal output given by converting the signals #5 (#6 signal in Timing Chart)
- © Time pulse signal output with the pulse-width proportional to distance from the nearest object(#⑦ signal in Timing Chart)
- d External Trigger / Monitor Terminal
 - Signal input terminal for External Trigger Mode (the pulse width from 0.5 ms to 1 ms and TTL level recommended)
 - Monitor terminal for Free Run Mode to see the Trigger Timing. Internal trigger signal is automatically generated.
- e GND
- (f) +Power : 6V~15V range input
- (g) Ultrasonic Sensor Terminal (Input terminal to and output terminal from a sensor)
- (h) Ultrasonic Sensor Terminal (GND and shield line)
- (i) 5V High signal output when a object is detected in arbitrary range
- ① 5V High signal output when detected in the range from 0 to 4 m
- (k) 5V High signal output when detected in the range from 0 to 3 m
- ① 5V High signal output when detected in the range from 0 to 2 m
- m 5V High signal output when detected in the range from 0 to 1 m

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 - **The principle to detect the object located within 40cm distance**
 - X Distance measurement is available only in the range longer than 40 cm. However, it is possible to get the on/off(existence or non-existence) signal even in the range shorter than 40 cm if multi-reflection wave signals are detected.



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Note : Sensor Mounting(Basic Type)



Edge Vibration Area

• Vibration area is extended to the side face as well as the top of a sensor



• The tight mounting of the side face in the top side of a sensor could interrupt normal vibration of the sensor.



• Use of a rubber packing or a soft gasket: Note not to interfere the vibration(acoustic sealing effect)



• In case of injection mold type platform, This structure is also good.



The drawing of sensor appearance